Math 222, Fall 2004: Final Exam

- Closed books, no notes, no calculators.
- Upper case letters denote matrices, boldface lower case letter vectors, and plain lower case letters scalars.
- The transpose of a matrix A is denoted A^{t} .
- The identity matrix is denoted *I*.
- A matrix U is said to be orthogonal if $U^{t}U = I$.
- In questions 2 6, please provide brief explanations for the steps in your calculations.

Question 1: There is no connection between the matrices and the vectors in the following questions. No motivation is required. (2p each)

- (a) Suppose that A is an $m \times n$ matrix of rank k. What is dim(Col(A))?
- (b) Suppose that there exists a non-zero vector \mathbf{y} such that $A\mathbf{y} = 0$. Does there exist a vector \mathbf{b} such that the equation $A\mathbf{x} = \mathbf{b}$ has a unique solution?
- (c) Is it true that λ is an eigenvalue of A if and only if det $(A \lambda I) = 0$?
- (d) Is it true that all square matrices are diagonalizable?
- (e) What conditions must a matrix satisfy for it to have a singular value decomposition?
- (f) Complete the sentence: If A and B are matrices, then every row of AB is a linear combination of the rows of the matrix
- (g) Suppose that \mathbf{q}_1 and \mathbf{q}_2 are two non-zero vectors in \mathbb{R}^n such that $\mathbf{q}_1 + t\mathbf{q}_2 \neq 0$ for all t. What is dim(Span{ $\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_1 + \mathbf{q}_2$ })?
- (h) Suppose that A is an $m \times n$ matrix of rank n, that $\mathbf{b} \in \operatorname{Col}(A)^{\perp}$ and that $\mathbf{b} \neq 0$. How many solutions does the equation $A\mathbf{x} = \mathbf{b}$ have?
- (i) Suppose that H is a subspace of \mathbb{R}^n of dimension k, where k < n. What is the dimension of H^{\perp} ?
- (j) Give a matrix A such that $2x_1^2 + x_1x_2 x_2^2 = \mathbf{x}^t A \mathbf{x}$, where $\mathbf{x}^t = [x_1 x_2]$.
- (k) What is the largest possible singular value of an orthogonal matrix?

Question 2: Consider the equation

(1)
$$A\mathbf{x} = \mathbf{b},$$

where

$$A = \begin{bmatrix} 1 & 1 & 2 & 1 & 0 \\ -1 & 1 & -2 & -1 & 1 \\ 1 & 1 & 2 & 2 & 1 \\ 1 & 5 & 2 & 2 & 3 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}, \quad \text{and} \quad \mathbf{b} = \begin{bmatrix} 2 \\ 1 \\ 0 \\ 6 \end{bmatrix}.$$

- (a) Find all **x** that solve (1). Your answer should either give an explicit formula for each x_i or indicate that it is a free variable. (10p)
- (b) Give a basis for Row(A). (5p)
- (c) Give a basis for $\operatorname{Col}(A)$. (5p)

Question 3: Consider \mathbb{P}^3 , the vector space of polynomials of degree 3 or less, and its subspace

$$H = \text{Span}\{1 + t + 2t^3, 1 + 3t - 4t^2, 2 + 2t + 4t^3, 1 + t + t^2 + 2t^3\}.$$

- (a) Does the vector $\mathbf{p}(t) = 2 + 2t t^2 + 4t^3$ belong to H? (7p)
- (b) What is the dimension of H? (3p)

Question 4: Consider the matrices

and set

$$A = U D U^{\mathrm{t}}.$$

Note that U is orthogonal.

- (a) What are the eigenvalues of A? (5p)
- (b) Let \mathbf{u}_2 denote the second column of U. What is $A\mathbf{u}_2$? (5p)
- (c) Determine an orthogonal matrix P, and a diagonal matrix E, such that $A^2 + A^{-1} = P E P^{t}$. (5p)

Question 5: Consider the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 1\\0\\1\\0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1\\1\\-1\\-2 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0\\0\\2\\6 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 1\\1\\1\\1 \end{bmatrix},$$

(note that $\mathbf{v}_1 \cdot \mathbf{v}_2 = 0$) and set

$$V = \operatorname{Span}\{\mathbf{v}_1, \, \mathbf{v}_2, \, \mathbf{v}_3\}.$$

- (a) Set $\mathbf{q}_1 = \mathbf{v}_1/||\mathbf{v}_1||$, $\mathbf{q}_2 = \mathbf{v}_2/||\mathbf{v}_2||$, and determine a vector \mathbf{q}_3 such that $\{\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3\}$ forms an orthonormal basis for V. (8p)
- (b) Set $A = [\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3], Q = [\mathbf{q}_1, \mathbf{q}_2, \mathbf{q}_3]$, and find an upper triangular matrix R such that A = QR. (6p)
- (c) Find a vector $\mathbf{z} \in V$ such that $||\mathbf{b} \mathbf{z}|| \le ||\mathbf{b} \mathbf{y}||$ for all $\mathbf{y} \in V$. (6p)

Question 6: If A is an $n \times n$ invertible matrix, and if **u** and **v** are $n \times 1$ vectors such that $A + \mathbf{u}\mathbf{v}^{t}$ is invertible, then

(2)
$$(A + \mathbf{u} \mathbf{v}^{\mathrm{t}})^{-1} = A^{-1} - \beta A^{-1} \mathbf{u} \mathbf{v}^{\mathrm{t}} A^{-1},$$

where

$$\beta = \frac{1}{1 + \mathbf{v}^{\mathrm{t}} A^{-1} \mathbf{u}}.$$

(a) Use formula (2) to compute the inverse of

$$B = \begin{bmatrix} 6 & 1 & 1 & 1 & 1 \\ 1 & 6 & 1 & 1 & 1 \\ 1 & 1 & 6 & 1 & 1 \\ 1 & 1 & 1 & 6 & 1 \\ 1 & 1 & 1 & 1 & 6 \end{bmatrix}.$$

(7p) Hint: Set $\mathbf{u} = \mathbf{v} = [1\,1\,1\,1\,1]^{t}$.

(b) Prove the formula (2). (8p) **Hint**: Set $X = A^{-1} - \beta A^{-1} \mathbf{u} \mathbf{v}^{t} A^{-1}$, prove that $(A + \mathbf{u} \mathbf{v}^{t}) XA = A$, and solve for X.

Remark: As a curiousity, the formula (2) is a special case of something called the Sherman-Morrison-Woodbury formula which says that

(3)
$$(A + UV^{t})^{-1} = A^{-1} - A^{-1}U(I + V^{t}A^{-1}U)V^{t}A^{-1},$$

where A is an invertible $n \times n$ matrix, and U and V are $n \times k$ matrices such that $A + UV^{t}$ is invertible. The formula (3) is very useful in cases where one knows A and wants to compute the inverse of a slightly perturbed version of A (say only a couple of elements changed).

/// PG Martinsson, Dec 17, 2004