1. LATENT SEMANTIC INDEXING

Monday, March 14, 2016:

1.1. Intuition. Objective is to classify bodies of text.

Idea: form a matrix B that records the incidence of words ("terms") in your database.

Then every term frequency - tf_{ij} of that matrix will be the number of times term *i* appears in document *j*. Typically, we would filter out the terms that don't carry much meaning.

1.2. Method. From B, we can construct a matrix A defined by:

$$\mathbf{A}_{ij} = \log (tf_{ij} + 1)(1 + \frac{\sum_{j=1}^{n} p_{ij} \log p_{ij}}{\log(n)})$$

where: $p_{ij} = \frac{tf_{ij}}{gf_i}$, $gf_i = \sum_{j=1}^n tf_{ij} = 1$ for any j.

Perform SVD on A:

 $\begin{array}{cccc} \mathbf{A} &\approx & \mathbf{T} & \mathbf{S} & \mathbf{D}^*.\\ m \times n & m \times k & k \times k & k \times n \end{array}$

where, T - term concept matrix, D - concept-document matrix

1.3. **Non-linear techniques.** Often, the relationship between the data is nonlinear. Approach to resolve such problem is *Kernel PCA*:

Kernel PCA:

We construct a non-linear transformation on the given data X such that PCA algorithm can pick out clusters. Problem with such algorithm is that it's hard to come up with a non-linear map that solved the problem of non-linearity.

Example: In the following example, we are given a data that forms two circles with different radius. A kernel trick that could easily distinguish the two datasets is to add a third dimension that is formed by $x^2 + y^2$ from existing dimensions of x and y. We see the result of such kernel map on the image.

2. DIFFUSION MAPS

2.1. Markov Chains review. Use distance between 2 points as a probability of jump in Markov chain matrix.

Markov Chains give us a way to estimate what event will be likely after arbitrary number of steps that the systems will take. For more intuition, let's consider an example.

Stock Market:

Say we have 3 states:

- (1) Bull
- (2) Bear
- (3) Stagnant

Given **P** - probability transition matrix, and $\$_0 = \begin{bmatrix} 1\\0\\0 \end{bmatrix}$ - initial distribution: $\mathbf{P} = \begin{bmatrix} 0.9 & 0.15 & 0.25\\0.075 & 0.8 & 0.25\\0.025 & 0.05 & 0.5 \end{bmatrix}.$



FIGURE 1. Original data (left), Kernel transformed data (right).

We can estimate that after 1 step, our distribution of each state will be as following:

$$\$_1 = \mathbf{P}\$_0 = \begin{bmatrix} 0.9\\ 0.075\\ 0.025 \end{bmatrix}$$

After infinitely many steps, in this example we would get a stationary distribution of. We can argue that a Markov Chain admits SVD :

$$\mathbf{P} = \mathbf{V} \Lambda \mathbf{V}^{-1}$$

, where:

$$\Lambda = \begin{bmatrix} \lambda_1 = 1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix}.$$

Then,

$$\mathbf{P}^{k} == \mathbf{V}\Lambda^{k}\mathbf{V}^{-1} = \mathbf{V} \begin{bmatrix} \lambda_{1}^{k} & 0 & \cdots & 0\\ 0 & \lambda_{2}^{k} & \cdots & 0\\ \vdots & \vdots & & \vdots\\ 0 & 0 & \cdots & \lambda_{n}^{k} \end{bmatrix} \mathbf{V}^{-1} \rightarrow \mathbf{V} \begin{bmatrix} 1 & 0 & \cdots & 0\\ 0 & 0 & \cdots & 0\\ \vdots & \vdots & & \vdots\\ 0 & 0 & \cdots & 0 \end{bmatrix} \mathbf{V}^{-1}$$

In our example:

$$\mathbf{P}^{k} = \begin{bmatrix} 0.625 & 0.625 & 0.625 \\ 0.3125 & 0.3125 & 0.3125 \\ 0.0625 & 0.0625 & 0.0625 \end{bmatrix}.$$

We see that we lost any knowledge of where we started, because all columns converged to the same vector.